

# Boundary stabilization of wave equation by means of a general multiplier technique

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Control and Inverse Problems in PDE : Theoretical and  
Numerical Aspects

# Stabilization problem

If  $\Omega$  is a regular bounded open set of  $\mathbb{R}^n$  ( $n \geq 2$ ), we consider the following wave problem :

$$(S) \begin{cases} u'' - \Delta u = 0 & \text{in } \Omega \times \mathbb{R}_+^*, \\ u = 0 & \text{on } \partial\Omega_D \times \mathbb{R}_+^*, \\ \partial_\nu u = -(m \cdot \nu)g(u') & \text{on } \partial\Omega_N \times \mathbb{R}_+^*, \\ u(0) = u^0 & \text{in } \Omega, \\ u'(0) = u^1 & \text{in } \Omega, \end{cases}$$

with  $(u_0, u_1) \in H_D^1(\Omega) \times L^2(\Omega) := H$  where

$$H_D^1(\Omega) = \{v \in H^1(\Omega); v = 0 \text{ on } \partial\Omega_D\}.$$

We assume :

- $\partial\Omega_N = \{x \in \partial\Omega, m(x) \cdot \nu(x) > 0\}$ ,
- $\partial\Omega_D = \{x \in \partial\Omega, m(x) \cdot \nu(x) \leq 0\}$  satisfies  $\mathcal{H}^{n-1}(\partial\Omega_D) > 0$ ,
- $g$  is a non-decreasing function such that, for some  $p \geq 1$  and  $k_+ \geq k_- > 0$  :

$$\forall s \in \mathbb{R}, \quad k_+ |s| \geq |g(s)| \geq k_- \min(|s|, |s|^p),$$

- $m$  is a  $\mathcal{C}^1$  vector field on  $\bar{\Omega}$  such that

$$\inf_{\bar{\Omega}} \operatorname{div}(m) > \sup_{\bar{\Omega}} (\operatorname{div}(m) - 2\lambda_m).$$

where  $\lambda_m$  denotes the smallest eigenvalue of the symmetric part of the gradient  $(\nabla m)^s$ .

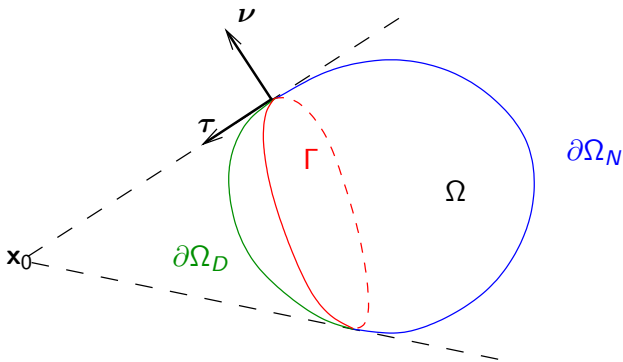


FIG.: Picture with  $m(x) = x - x_0$ .

- 1 Let us define the energy function

$$E(t, u) = \frac{1}{2} \int_{\Omega} (u'(t))^2 + |\nabla u(t)|^2 dx.$$

Our purpose is to obtain some decay estimates of  $E(t, u)$  with respect to time.

- 2 Formally, the time derivative of  $E$  is

$$E'(t, u) = - \int_{\partial\Omega_N} (m.\nu)g(u'(t))u'(t)d\sigma$$

- 3 The domain  $\mathcal{D}$  associated to the wave operator is

$$\left\{ (u, v) \in \left( H_D^1(\Omega) \right)^2 ; \Delta u \in L^2(\Omega), \partial_\nu u = -(m.\nu)g(v) \text{ on } \partial\Omega_N \right\}$$

- [KZ] Komornik, V., Zuazua, E., 1990, J. Math. pures et appli.,
- [BLM] Bey, R., Lohéac, J.-P., Moussaoui, M., 1999, J. Math. pures et appli.,
- [O] Osses, A., 2001, SIAM J. Control Optim.,
- [CLO] Cornilleau, P., Lohéac, J.-P., Osses, A.. To appear in J.D.C.S., 2009.

## Theorem

Let  $n \geq 2$  and  $\Gamma = \overline{\partial\Omega_D} \cap \overline{\partial\Omega_N}$ , let  $u \in H^1(\Omega)$  such that

$$\Delta u \in L^2(\Omega), \quad u|_{\partial\Omega_D} \in H^{3/2}(\partial\Omega_D), \quad \partial_\nu u|_{\partial\Omega_N} \in H^{1/2}(\partial\Omega_N).$$

Then,  $2\partial_\nu u(m \cdot \nabla u) - (m \cdot \nu)|\nabla u|^2 \in L^1(\partial\Omega)$  and there exists  $\zeta \in H^{\frac{1}{2}}(\Gamma)$  such that

$$2 \int_{\Omega} \Delta u (m \cdot \nabla u) dx = \int_{\Omega} (\operatorname{div}(m)I - 2(\nabla m)^s)(\nabla u, \nabla u) dx \\ + \int_{\partial\Omega} (2\partial_\nu u (m \cdot \nabla u) - (m \cdot \nu)|\nabla u|^2) d\sigma + \int_{\Gamma} (m \cdot \tau)|\zeta|^2 d\gamma$$

## Remark

The last term has to be understood in the summation over the discrete set  $\Gamma$  if  $n = 2$ .

## Remark

- One shows that under these hypotheses,  $u$  can be written as the sum of a part which belongs to  $H^2(\Omega)$  and the solution of a mixed problem :

$$\begin{cases} -\Delta u_S = f & \text{in } \Omega, \\ u_S = 0 & \text{on } \partial\Omega_D, \\ \partial_\nu u_S = 0 & \text{on } \partial\Omega_N. \end{cases}$$

for some  $f \in L^2(\Omega)$ .

This solution is basically a coefficient  $\zeta$  times a singular function, which brings the last term in Rellich's identity.

- For  $n = 2$ , the singular function is the well-known Shamir function on the domain  $\Omega_0 = \{(r, \theta), 0 \leq r \leq 1, 0 \leq \theta \leq \pi\}$  :

$$U_s(r, \theta) = \rho(r)\sqrt{r} \sin\left(\frac{\theta}{2}\right).$$

For the stabilization result, we only need

$$2 \int_{\Omega} \Delta u (m \cdot \nabla u) dx \leq \int_{\Omega} (\operatorname{div}(m) I - 2(\nabla m)^s)(\nabla u, \nabla u) dx \\ + \int_{\partial\Omega} (2\partial_{\nu} u (m \cdot \nabla u) - (m \cdot \nu) |\nabla u|^2) d\sigma$$

## Theorem

Assuming that  $m \cdot \tau \leq 0$  on  $\Gamma$ ; then, for every  $(u_0, u_1) \in H$ , there exists  $C, T > 0$  such that the energy of the solution  $u$  of (S) satisfies :

$$\text{if } p = 1, \quad E(u, t) \leq E(u, 0) \exp\left(1 - \frac{t}{C}\right) \quad \forall t > T, \\ \text{if } p > 1, \quad E(u, t) \leq Ct^{2/(1-p)} \quad \forall t > T.$$

## Remarks

- $C$  depends on the initial energy  $E(u, 0)$  in the second case, not in the first,

## Remarks

- this result extends previous ones :

BLM  $m(x) = (x - x_0),$

CLO  $m(x) = (dl + A)(x - x_0)$  with  $A$  a skew-symmetric matrix,

## Remarks

- new cases are given by this framework :
  - 1  $m(x) = (A_1 + A_2)(x - x_0)$  with  $A_1$  some positive definite matrix and  $A_2$  any skew symmetric matrix,
  - 2  $m(x) = (dl + A)(x - x_0) + F(x)$  with  $\|(\nabla F)^s\|_\infty < \frac{d}{n}$  and  $A$  a skew-symmetric matrix.

# Sketch of proof for Rellich's relations

Away from the interface  $\Gamma$ , the solution is regular. Hence, with  $\Omega_\varepsilon = \{x \in \Omega; d(x, \Gamma) > \varepsilon\}$ , we have the following identity :

Rellich identity in regular case

$$2 \int_{\Omega_\varepsilon} \Delta u (m \cdot \nabla u) dx = \int_{\Omega_\varepsilon} (\operatorname{div}(m)I - 2(\nabla m)^s)(\nabla u, \nabla u) dx \\ + \int_{\partial\Omega_\varepsilon} (2\partial_\nu u (m \cdot \nabla u) - (m \cdot \nu) |\nabla u|^2) d\sigma.$$

# Sketch of proof for Rellich's relations

Let's define :  $\widetilde{\partial\Omega}_\varepsilon = \partial\Omega_\varepsilon \cap \partial\Omega$ ,  $\partial\Omega_\varepsilon^* = \partial\Omega_\varepsilon \cap \Omega$ .

- We now analyze the behavior of each integral terms on  $\Omega_\varepsilon$  or  $\widetilde{\partial\Omega}_\varepsilon$  thanks to Lebesgue's theorems : their limits are the corresponding terms on  $\Omega$  or  $\partial\Omega$ .
- The remaining term to treat is

$$I_\varepsilon(\nabla u) = \int_{\partial\Omega_\varepsilon^*} 2\partial_\nu u(m \cdot \nabla u) - (m \cdot \nu)|\nabla u|^2 d\sigma.$$

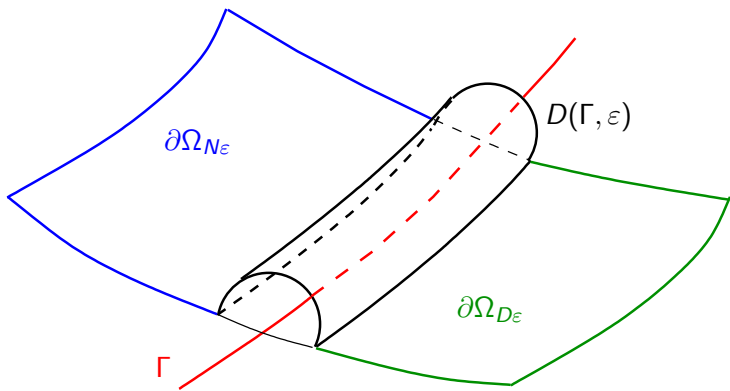


FIG.: Picture of  $\partial\Omega_\varepsilon^*$  and  $\widetilde{\partial\Omega_\varepsilon}$

# Behavior of $I_\varepsilon(\nabla u)$

We first split, locally near any point  $x^* \in \Gamma$ , the gradient of  $u$  in its component along  $\Gamma$  and  $\langle \nu^*, \tau^* \rangle$  :

$$\nabla u = \nabla_T u + \nabla_2 u.$$

Regularity result on  $\nabla_T u$  shows that it suffices to study  $I_\varepsilon(\nabla_2 u)$ . We now split  $u$  in  $u_R + \eta \otimes U_s^{x^*}$ , its regular part and singular part. Using regularity of  $u_R$ , we only have to deal with the following term

$$\int_{C_\varepsilon(x^*)} 2(\nu \cdot \nabla U_s^{x^*})(m \cdot \nabla U_s^{x^*}) - (m \cdot \nu) |\nabla U_s^{x^*}|^2 dl$$

and this can be done using the following elementary identity :

$$2\partial_\nu U_s^{x^*} (m \cdot \nabla U_s^{x^*}) - (m \cdot \nu) |\nabla U_s^{x^*}|^2 = \frac{1}{4\varepsilon} m \cdot \tau^* \text{ on } C_\varepsilon(x^*).$$

# Sketch of proof for stabilization

## Proposition (Komornik)

Let  $E : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  a non-increasing function such that there exists  $q \geq 0$  and  $C > 0$  which fulfill :

$$\forall t \geq 0, \int_t^\infty E^{q+1}(s) ds \leq CE(t).$$

Then, setting  $T = CE^q(0)$ , one has :

$$\text{if } q = 0, \quad E(t) \leq E(0) \exp\left(1 - \frac{t}{T}\right) \quad \forall t \geq T,$$

$$\text{if } q > 0, \quad E(t) \leq E(0) \left(\frac{T + qT}{T + qt}\right)^{\frac{1}{q}} \quad \forall t \geq T.$$

► We already know that, under the hypotheses on  $g$  and  $m$ , the energy is non increasing; **it remains to check the integral inequality.**

# The multiplier method

The main idea is thus to perform the multiplier method for

$$Mu := \alpha u + 2m \cdot \nabla u,$$

which gives an energy estimate for strong solutions :

## Lemma

There exists  $c(\alpha) > 0$  such that, for any  $0 \leq S < T < \infty$  :

$$\begin{aligned} c(\alpha) \int_S^T E^{\frac{p-1}{2}} \left( \int_{\Omega} (u')^2 + |\nabla u|^2 dx \right) dt \leq \\ \left[ E^{\frac{p-1}{2}} \left( \int_{\Omega} u' M u dx \right) \right]_S^T + \frac{p-1}{2} \int_S^T E^{\frac{p-3}{2}} E' \left( \int_{\Omega} u' M u dx \right) dt \\ + \int_S^T E^{\frac{p-1}{2}} \left( \int_{\partial\Omega_N} (m \cdot \nu) ((u')^2 - |\nabla u|^2 - g(u') M u) d\sigma \right) dt. \end{aligned}$$

# The multiplier method

We obtain, using that  $(u(t), u'(t)) \in \mathcal{D}$  for all  $t$  and Rellich's relations, an estimate of the integral on  $[S, T]$  of the term

$$E^{\frac{p-1}{2}} \int_{\Omega} (\operatorname{div}(m) - \alpha)(u')^2 + ((\alpha - \operatorname{div}(m))I + 2(\nabla m)^s)(\nabla u, \nabla u) dx.$$

Let us choose  $\alpha$  so that, uniformly on  $\Omega$ ,

$$\begin{aligned} \operatorname{div}(m) - \alpha &> 0, \\ (\alpha - \operatorname{div}(m))I + 2(\nabla m)^s &\text{ is positive definite.} \end{aligned}$$

The optimal choice of  $\alpha$  consequently gives

$$c = \frac{1}{2} \left( \inf_{\bar{\Omega}} \operatorname{div}(m) - \sup_{\bar{\Omega}} (\operatorname{div}(m) - \lambda_m) \right).$$

# Sketch of proof for stabilization

Now, we estimate the right hand side terms using some routine inequalities :

- Young's is very useful in all this situation : it allows us to estimate the term  $\int_{\partial\Omega_N} (m.\nu)g(u')Mud\sigma$ ,
- Poincaré's is used to estimate the term  $\int_{\partial\Omega_N} u^2 m.\nu d\sigma$ ,
- Jensen's is used for the term  $\int_{\partial\Omega_N} ((u')^2 + g(u')^2)m.\nu d\sigma$ .

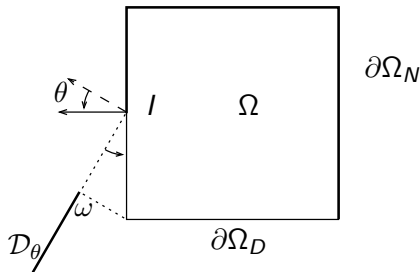
We finally obtain, for every  $\varepsilon < \varepsilon_0$  :

$$2c \int_S^T E^{\frac{p+1}{2}} dt \leq C(\varepsilon)E(S) + \varepsilon C \int_S^T E^{\frac{p+1}{2}} dt.$$

which gives the result for sufficiently small  $\varepsilon$ .

# Numerical aspects

We choose  $\Omega = (0, 1)^2$  and the rotated multiplier  $m(x) = R_\theta(x - x_0)$ , where  $x_0 \in \mathcal{D}_\theta$ .



**FIG.:** When  $x_0$  belongs to  $\mathcal{D}_\theta$ , our geometrical condition is satisfied at  $l = (0, 1/2)$ .

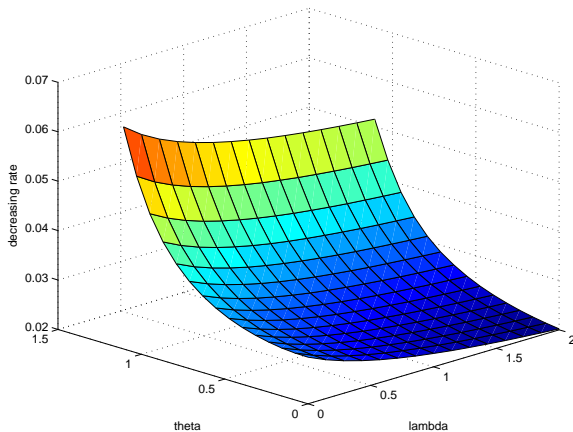


FIG.: Dependence of the decreasing rate with respect to  $\lambda = |x_0 - \omega|$ ,  $\theta$ .

- **Delayed wave equation** We also obtained an exponential stabilization result in the case of a boundary feedback law

$$\partial_\nu u + (m \cdot \nu) \mu_0 u'(t) + (m \cdot \nu) \int_0^t u'(t-s) d\mu(s) = 0 \text{ on } \partial\Omega_N.$$

if, for some  $\alpha > 0$ ,  $\int_0^\infty e^{\alpha s} d|\mu|(s) < \mu_0$ .

- **A lot remains to be done...**
  - 1 If  $n = 2$ , we also know that if  $\partial\Omega$  is piecewise  $\mathcal{C}^2$ , Rellich's relations remains true if the angles on  $\Gamma$  are convex. What happens if  $n \geq 3$ ?
  - 2 It seems that the condition  $m \cdot \tau \leq 0$  on  $\Gamma$  is unnecessary to get stabilization results, but we don't have any proof yet.